

Standard optical

Sendix Base KIS50 / KIH50 (shaft / hollow shaft)

Push-pull / RS422 / Open collector



The encoders Sendix Base KIS50 / KIH50 offer a protection level up to IP65 and can be used with temperatures from -20°C up to +70°C. They are ideal for use in standard applications and in simple machines.

The Sendix Base KIS50 / KIH50 family also features our well proven Safety-Lock™ system, allowing higher tolerance of possible installation errors and increasing the overall performance of this encoder

























High rotational

Temperature

High protection

capacity

resistant

proof

proof

protection

Robust

- · Resistant die-cast housing and protection up to IP65.
- Wide temperature range, -20°C ... +70°C.
- · Elimination of machine downtime thanks to sturdy bearing construction in "Safety-Lock™ Design".

Flexible

- · Suitable connection variant for every specific case: cable connection, M12 and M23 connector.
- · Various mounting options.
- Up to 5000 pulses per revolution.

Order code **Shaft version**

8.KIS50







8 = clamping flange, IP65 ø 58 mm [2.28"]

B = synchro flange, IP65 ø 58 mm [2.28"]

Shaft (ø x L), with flat

 $1 = \emptyset 6 \times 10 \text{ mm} [0.24 \times 0.39"]$

 $6 = \emptyset 8 \times 15 \text{ mm} [0.32 \times 0.59"]$

 $3 = \emptyset 10 \times 20 \text{ mm} [0.39 \times 0.79"]$ $5 = \emptyset 12 \times 20 \text{ mm} [0.47 \times 0.79"]$

Output circuit / power supply

4 = RS422 (with inverted signal) / 5 V DC

1 = RS422 (with inverted signal) / 5 ... 30 V DC

2 = push-pull (7272 compatible with inverted signal) / $5 \dots 30 \text{ V DC}$

5 = push-pull (with inverted signal) / 10 ... 30 V DC

3 = open collector (with inverted signal) / 5 ... 30 V DC

d Type of connection

1 = axial cable, 1 m [3.28'] PVC

2 = radial cable, 1 m [3.28'] PVC

3 = axial M12 connector, 8-pin

4 = radial M12 connector, 8-pin

7 = axial M23 connector, 12-pin

8 = radial M23 connector, 12-pin

Pulse rate

100, 200, 250, 256, 360, 500, 512, 600, 1000, 1024, 2000, 2048, 2500, 3600, 4096, 5000

(e.g. 100 pulses => 0100)

Order code **Hollow shaft**

8.KIH50







2 = with spring element, long, IP65

4 = with torque stop, long, IP65

D = with stator coupling, IP65, ø 63 mm [2.48"]

b Through hollow shaft

 $9 = \emptyset 8 \text{ mm } [0.32"]$ $3 = \emptyset 10 \text{ mm } [0.39"]$

 $5 = \emptyset 12 \text{ mm } [0.47"]$

 $A = \emptyset 14 \text{ mm } [0.55"]$

 $8 = \emptyset 15 \text{ mm } [0.59"]$

© Output circuit / power supply

4 = RS422 (with inverted signal) / 5 V DC

1 = RS422 (with inverted signal) / 5 ... 30 V DC

2 = push-pull (7272 compatible with inverted signal) / 5 ... 30 V DC

5 = push-pull (with inverted signal) / 10 ... 30 V DC

3 = open collector (with inverted signal) / 5 ... 30 V DC

d Type of connection

1 = radial cable, 1 m [3.28'] PVC

2 = radial M12 connector, 8-pin

4 = radial M23 connector, 12-pin

E = tangential cable, 1 m [3.28'] PVC

Pulse rate

100, 200, 250, 256, 360, 500, 512, 600, 1000, 1024, 2000, 2048, 2500, 3600, 4096, 5000

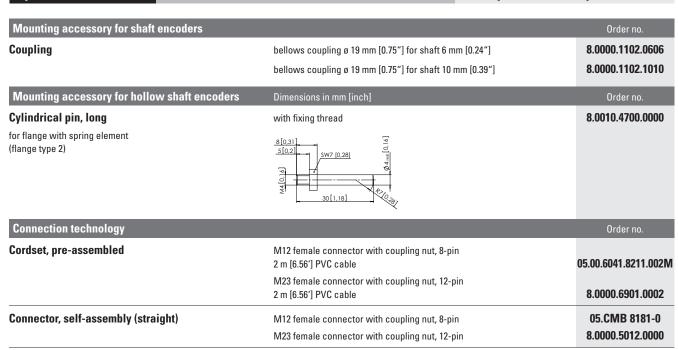
(e.g. 100 pulses => 0100)



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Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories.

Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology.

Technical data

Mechanical characteristics				
Maximum speed	6000 min ⁻¹	Weight	approx. 0.4 kg [14.11 oz]	
	3000 min ⁻¹ (continuous)	Protection acc. to EN 60529	IP65	
Mass moment of inertia		Working temperature range	-20°C +70°C [-4°F +158°F]	
shaft version hollow shaft version		Material shaft	stainless steel	
Starting torque at 20°C [68°F]	< 0.01 Nm	Shock resistance acc. to EN 60068-2-27	1000 m/s ² , 6 ms	
Shaft load capacity radial axial	80 N 40 N	Vibration resistance acc. to EN 60068-2-6	100 m/s², 10 2000 Hz	

Electrical characteristics					
Output circuit Order co	RS422 (TTL compatible ode 1	RS422 (TTL compatible) 4	Push-pull 5	Push-pull (7272 compatible) 2	Open collector (7273) 3
Power supply	5 30 V DC	5 V DC (±5 %)	10 30 V DC	5 30 V DC	5 30 V DC
Power consumption (no load)	typ. 40 mA max. 90 mA	typ. 40 mA max. 90 mA	typ. 50 mA max. 100 mA	typ. 50 mA max. 100 mA	100 mA
Permissible load / channel	max. +/- 20 mA	max. +/- 20 mA	max. +/- 20 mA	max. +/- 20 mA	20 mA sink at 30 V DC
Pulse frequency	max. 300 kHz	max. 300 kHz	max. 300 kHz	max. 300 kHz ¹⁾	max. 300 kHz
- 3	GH min. 2.5 V DW max. 0.5 V	min. 2.5 V max. 0.5 V	min +V - 1.0 V max. 0.5 V	min. +V - 2.0 V max. 0.5 V	
Rising edge time t _r	max. 200 ns	max. 200 ns	max. 1 µs	max. 1 μs	
Falling edge time t _f	max. 200 ns	max. 200 ns	max. 1 μs	max. 1 μs	
Short circuit proof outputs 2)	yes ³⁾	yes ³⁾	yes	yes	yes
Reverse polarity protection of the power supply	yes	no	yes	no	no
CE compliant acc. to	EMC guideline 2 RoHS guideline				

¹⁾ Max. recommended cable length 30 m [98.43'].

²⁾ If power supply correctly applied.

³⁾ Only one channel allowed to be shorted-out: at +V= 5 V DC, short-circuit to channel, 0 V, or +V is permitted. at +V= 5 ... 30 V DC, short-circuit to channel or 0 V is permitted.



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Terminal assignment

Output circuit	Type of c	onnection	Cable (isolate unused cores individually before initial start-up)											
Output on our	KIS50:	1, 2	Signal:	0 V	+V	0 Vsens	+Vsens	A	Ā	В	B	0	0	Ť
1, 2, 3, 4, 5		•								_		-	-	_
	KIH50:	1, E	Core color:	WH	BN	GY PK	RD BU	GN	YE	GY	PK	BU	RD	shield
Output circuit	Type of c	onnection	M12 connecto	r, 8-pin										
1, 2, 3, 4, 5	KIS50:	3, 4	Signal:	0 V	+V	0 Vsens	+Vsens	А	Ā	В	B	0	0	Ť
1, 2, 3, 4, 3	KIH50:	2	Pin:	1	2			3	4	5	6	7	8	PH ¹⁾
Output circuit	Type of c	onnection	M23 connecto	r, 12-pin										
1, 2, 3, 4, 5	KIS50:	7, 8	Signal:	0 V	+V	0 Vsens	+Vsens	Α	Ā	В	B	0	ō	Ť
1, 4, 3, 4, 3	KIHEU.	1	Din:	10	12	11	2	5	6	Q	1	2	1	рц 1)

+V: Encoder power supply +V DC

0 V: Encoder power supply ground GND (0 V)

0 Vsens / +Vsens: Using the sensor outputs of the encoder, the voltage

present can be measured and if necessary increased

accordingly.

 $\begin{array}{ll} A,\,\overline{A}; & \quad \text{Incremental output channel A} \\ B,\,\overline{B}; & \quad \text{Incremental output channel B} \end{array}$

0, $\overline{0}$: Reference signal

PH \(\frac{1}{2}\): Plug connector housing (shield)

Top view of mating side, male contact base





M12 connector, 8-pin

M23 connector, 12-pin

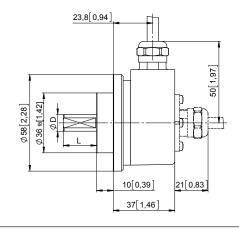
Dimensions shaft version

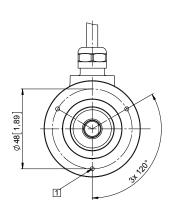
Dimensions in mm [inch]

Clamping flange, ø 58 [2.28] Flange type 8

1 3 x M3, 6 [0.24] deep

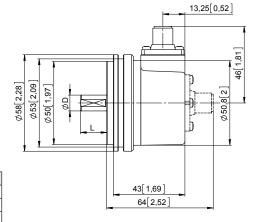
D	Fit	L
6 [0.24]	h7	10 [0.39]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
12 [0.47]	h7	20 [0.79]

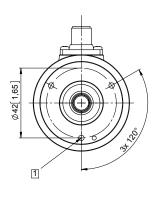




Synchro flange, ø 58 [2.28] Flange type B

1 3 x M4, 6 [0.24] deep





D	Fit	L
6 [0.24]	h7	10 [0.39]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
12 [0.47]	h7	20 [0.79]

¹⁾ PH = shield is attached to connector housing.



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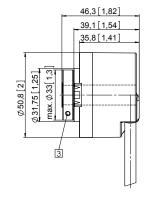
Dimensions hollow shaft version

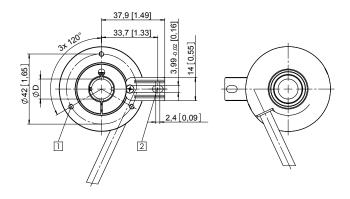
Dimensions in mm [inch]

Flange with spring element, long Flange type 2

- 1 3 x M3, 6 [0.24] deep
- 2 Slot spring element, recommendation: cylindrical pin DIN 7, ø 4 [0.16]
- 3 Recommended torque for the clamping ring 0.6 Nm

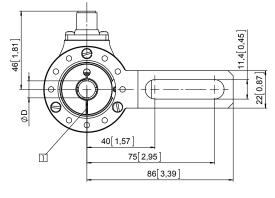
D	Fit
8 [0.32]	H7
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7

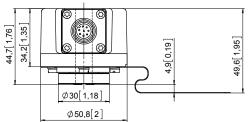




Flange with torque stop, long Flange type 4

1 Recommended torque for the clamping ring 0.6 Nm





D	Fit
8 [0.32]	H7
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7

Flange with stator coupling, ø 63 [2.48] Flange type D

1 Recommended torque for the clamping ring 0.6 Nm

D	Fit
8 [0.32]	H7
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7

